

Vane motor high performance hydraulic series M5B - M5BS - M5BF





	CHARA	CTERISTICS - M5B*	SERIES			
LOW NOISE MOTOR	12 vanes and a patented cartridge design allow a very low noise level, whatever the speed.					
HIGH PERFORMANCE MOTOR	The M5B series has been designed especially for severe duty applications wich require high pressure , high speed and low fluid lubricity.Max. pressure (intermittent)M5B* 012 to 036: 4650 PSI M5B* 045: 4060 PSI					
	Max. spe	eed (intermittent, low le	oaded cond.) M M M	[5B* 012 - 018 [5B* 023 - 036 [5B* 045	: 6000 RPM : 4000 RPM : 3000 RPM	
HIGH EFFICIENCY	Up to 90 Vane mo througho Vane pir	% overall at 4650 PSI otors begin life with a but their operating life. holdout design impro	high volumetric	efficiency, and cal efficiency a	d maintain that efficiency at low pressure.	
HIGH STARTING TORQUE	The high high load	a starting torque efficient without pressure over	ency of the vane rshoots, jerks and	type motors a d high instanta	llows them to start under neous horsepower loads.	
LOW TORQUE RIPPLE	This 12 speeds.	This 12 vane type motor exhibits a very low torque ripple (typical \pm 1,5%), even at low speeds.				
HIGH LIFETIME	The vane, rotor and cam ring are pressure balanced to increase life over the full speed range. Double lip vanes reduce the sensitivity to fluid pollution.					
INTERCHANGEABLE ROTATING GROUPS	Our precise manufacturing allows any component to be interchangeable. Rotating groups may be easily replaced to renew the motor or change the displacement to suit altered requirements for speed or torque.					
ROTATION AND DRAIN	The M5B-M5BS are bi-directional motors, externally drained. The M5BF, externally drained, is available in three types of rotation : bi-directional, clockwise, counter-clockwise. The M5BF1, internally drained, is available in two types of rotation : clockwise, and counter-clockwise.					
CROSS PORT CHECK VALVE	The uni-directional M5BF and M5BF1 are designed with an internal valve that allows smooth dynamic braking, with a very simple hydraulic circuit and without risk of motor cavitation.					
MOUNTING	M5B - M5BS : Cylindrical keyed or splined shaft according to SAE J744, ISO 3019-2 or J498b. These products are designed primarily for coaxial drives which do not impose axial or side loading on the shaft. M5BF : A stiff taper or cylindrical keyed shaft and a high load capacity double ball bearing allow the direct mounting on shaft (fan _)					
		ISO 3019-2	Ports	Drain	Shatt ends Keyed cyl. SAE "B"	
	M5B	100 A2/B4 HW (2/4 bolts - 3.94 DIA)	SAE 3/4" 4 bolts	M18 x .06	or Keyed cyl. ISO E 25M	
	M5BS	SAE "B" J744c (2/4 bolts - 4.00 DIA)	UNC or metric threads	M18 x .06	or Splined SAE "B"	
	M5BF	Special mounting (2 bolts - 5.31 DIA)	(ISO/DIS 6162 SAE J518c)	or SAE 9/16"	Keyed taper non SAE Keyed cyl. SAE "C" Keyed cyl. ISO G32N	

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DESCRIPTION - M5B* SERIES



OPERATION -SINGLE CARTRIDGE

- The motor shaft is driven by the rotor. Vanes, closely fitted into the rotor slots move radially to seal against the cam ring. The ring has two major and two minor radial sections joined by transitional sections called ramps. These contours and the pressures exposed to them are balanced diametrically.
- Hydraulic pins and light springs urge the vanes radially against the cam contour assuring a seal at zero speed so that the motor can develop starting torque. The springs and pins are assisted by centrifugal force at higher speeds. Radial grooves and holes through the vanes equalize radial hydraulic forces on the vanes at all times. Fluid enters and leaves the motor cartridge through opening in the side plates at the ramps. Each motor port connects to two diametrically opposed ramps. Pressurized fluid entering at Port A torques the rotor clockwise. The rotor transports it to the ramp openings which connect to Port B from which it returns to the low pressure side of the system. Pressure at Port B torques the rotor counter-clockwise.
- The rotor is separated axially from the sideplate surfaces by the fluid film. The front sideplate is clamped against the cam ring by the pressure, maintains optimum clearance as dimensions change with temperature and pressure. A 3-way shuttle valve in the sideplate causes clamping pressure in Port A or B, whichever is the highest.
- Materials are chosen for long life efficiency. The vanes, rotor and cam ring are made out of hardened high alloy steels. Cast semi-steel sideplates are chemically etched to have a fine crystalline surface for good lubrication at start-up.

PORT	S AND HYDRAULIC FLUIDS - M5B* SERIES
EXTERNAL DRAIN MOTOR	This motor may be alternately pressurized on ports A and B to 4650 PSI max. Whichever port is at low pressure, it should not be subjected to more than 60% of the high pressure, eg : When 4650 PSI in A, B is limited to 2900 PSI.
	This motor must have a drain line connected to the center housing drain connection of sufficient size to prevent back pressure in excess of 50 PSI, and returned to the reservoir below the surface of the oil as far away as possible from the suction pipe of the pump.
INTERNAL DRAIN MOTOR	This unidirectional motor may be pressurized only on the port corresponding to its rotation type. The outlet pressure must not be higher than 50 PSI.
RECOMMENDED FLUIDS	Petroleum base anti-wear R & O fluids (covered by DENISON HF-0 and HF-2 specifications). Maximum catalog ratings and performance data are based on operation with these fluids.
FIRE RESISTANT FLUIDS	They are easily used in the M5B* motor. These include phosphate or organic ester fluids and blends, water-glycol solutions and water-oil invert emulsions.
ACCEPTABLE ALTERNATE FLUIDS	The use of fluids other than petroleum base anti-wear R & O fluids requires that the maximum ratings of the motor will be reduced. In some cases, the minimum replenishment pressure must be increased.
	$\begin{array}{ll} \text{HF-1: non antiwear petroleum base.} \\ \text{HF-3: water in oil emulsion.} \\ \text{HF-4: water glycols.} \\ \text{HF-5: synthetic fluids.} \\ \text{Max. press. int.:} & 3500 \text{ PSI (HF-1, HF-4, HF-5)} \\ & 2500 \text{ PSI (HF-3)} \\ \text{Max. press. cont.:} & 3000 \text{ PSI (HF-1, HF-4, HF-5)} \\ & 2000 \text{ PSI (HF-3)} \\ \text{Max. speed:} & 1800 \text{ RPM (HF-3, HF-4, HF-5)} \\ \end{array}$
VISCOSITY	Max. (cold start, low speed and pressure) 4000 SUS Max. (full speed and pressure) 500 SUS Optimum (max. lifetime) 140 SUS Min. (full speed and pressure, HF-1 fluid) 90 SUS Min. (full speed and pressure, HF-0 & HF-2 fluids) 60 SUS For cold starts, the motor should operate at low speed and pressure until fluid warms up to an acceptable viscosity for full power operation.
VISCOSITY INDEX	90 min. Higher values extend the range of operating temperatures and lifetime.
TEMPERATURE	Max. fluid temperature (HF-0, HF-1 & HF-2) + 212° F Min. fluid temperature (HF-0, HF-1 & HF-2) - 0.4° F
FLUID CLEANLINESS	The fluid must be cleaned before and during operation to maintain a contamination level of NAS 1638 class 8 (or ISO 18/14) or better. Filters with 25 micron (or better, $\beta 10 \ge 100$) nominal ratings may be adequate but do not guarantee the required cleanliness levels.
WATER CONTAMINATION IN FLUID	 Maximum acceptable content of water is : 0,10 % for mineral base fluids 0,05 % for synthetic fluids, crankcase oils, biodegradable fluids. If amount of water is higher, then it should be drained off the circuit.

MINIMUM REPLENISHMENT PRESSURE (PSI ABSOLUTE)

	Speed [RPM] - Oil viscosity = 150 SUS						
	500	1000	2000	3000	4000		
M5B*	20.3	24.7	39.1	60.9	87.0		

The inlet port of the motor must be supplied with replenishment pressure as listed above to prevent cavitation during dynamic braking. This pressure should be multiplied by a coefficient of 1,5 when used with fire resistant fluids (HF-3, HF-4, HF-5).

MOTOR SELECTION - M5B* SERIES

Motor performa	nces	required	
Torque	Т	[in.lbf]	970
Speed	п	[RPM]	1500
Pump available	date	ı	
Flow	q_V	e [GPM]	14.5
Pressure	р	[PSI]	4060

1. Check if available power is greater than required power (0.85 estimated overall efficiency). $0.85 \ x \ \frac{q \ ve \, x \, p}{1714} \ge \frac{T \, x \, n}{63 \ 000}$

$$0.85 \ x \ \frac{14.5 \ x \ 4060}{1714} \ge \frac{970 \ x \ 1500}{63 \ 000}$$

 $V_{i} = \frac{231 x q_{Ve}}{n} = \frac{231 x 14.5}{1500} = 2.23 in^{3} / rev.$

3b. Choose motor from V_i immediately

4b. Check theoretical motor press. with

 $p = \frac{2\pi x T}{V_i} = \frac{2\pi x 970}{2.20} = 2770 PSI$ *Torque loss at this pressure = 70 in.lbf*

 $M5B^* 036$: $V_i = 2.20 \text{ in}^3/\text{rev.}$

<u>Two ways of calculation</u>: Calculate V_i from T required torque, or from q_{Ve} available flow

2b.

smaller

T = 970 in.lbf

(See page 6)

(See page 6)

Calculate real pressure $p = \frac{2\pi x (T+Tl)}{T} =$ V_i

 $\frac{2 \pi x \, 1040}{2.20} = 2970 \, PSI$

Real flow used by the motor :

14.5 - 1.1 = 13.4 GPM

p = 2970 PSI

5b. Flow loss at this pressure : 1.1 GPM

2a.
$$V_i = \frac{2 \pi x T}{p} = \frac{2 \pi x 970}{4060} = 1.50 \text{ in}^3/\text{rev}$$

29.2 > 23.1 HP

3a. Choose motor from V_i immediately greater $M5B^* 028$: $V_i = 1.71 \text{ in}^3/\text{rev}$.

4a. Check theoretical motor pressure

$p = \frac{2 \pi x T}{V_i} = \frac{2 \pi x 970}{1.71} = 3560 PSI$
<i>Torque loss at this pressure = 85 in.lbf</i>
(See page 6)
Calculate real pressure
$2\pi x(T+Tl)$
$p = \frac{V_i}{V_i} =$
$2\pi x 1055$
$\frac{1.71}{1.71} = 3880 PSI$

5a. Flow loss at this pressure : 1.3 GPM (See page 6) Real flow used by the motor : 14.5 - 1.3 = 13.2 GPM

3880 PSI

р =

6a. Real speed of the motor : $n = \frac{q_V x 231}{V_i} = \frac{13.2 x 231}{1.71} = 1780 RPM$	6b. Real speed of the motor : $n = \frac{q_V x 231}{V_i} = \frac{13.4 x 231}{2.20} = 1410 RPM$
Real performances	Real performances
$V_i = 1.71 \text{ in}^3/\text{rev.}$	$V_i = 2.20 \text{ in}^3/\text{rev.}$
n = 1780 RPM	n = 1410 RPM
T = 970 in.lbf	T = 970 in.lbf

In each case always choose the smallest motor which will operate at the highest speed and pressure, and will offer the most efficient solution.

FLUID POWER FORMULAS

Volumetric efficiency		$\frac{1}{1 + \frac{total \ leakage x \ 231}{speed \ x \ displacement}}$	Speed Displacement	[RPM] [in ³ /rev]
Mechanical efficiency		$1 - \frac{\text{torque loss } x \ 2 \ \pi}{\Delta \text{ pressure } x \text{ displacement}}$	∆ pressure Flow rate Leakage	[PSI] [GPM] [GPM]
Fluid motor speed	RPM	$\frac{231 \ x \ flow \ rate}{displacement} x \ volumetric \ eff.$	Torque Torque loss	[in.lbf] [in.lbf]
Fluid motor torque	in.lbf	$\frac{\Delta \text{ pressure x displacement}}{2 \pi} \text{ x mech. eff.}$		
Fluid motor power	HP	$\frac{speed\ x\ displacement x\ \Delta\ pressure}{395934} x\ overall\ eff.$		
	HP	torque x speed 63 000		

PERFORMANCE DATA - M5B* SERIES

Series	Cartridge	Theoretical displacement	Theoretical torque	Theoretical power at 100 RPM	Typical data 2000 RPM - 4650 PSI	
		in ³ /rev	in-lbf/PSI	HP/100 PSI	in/lbf	HP
	012	0.73	0,116	0,0184	447.8	14.2
	018	1.10	0,175	0,0278	718.6	22.8
M5B*	023	1.40	0.223	0.0354	943.4	29.9
	028	1.71	0,272	0,0432	1169.0	37.1
	036	2.20	0,350	0,0536	1529.2	48.5
	045	2.75	0,437	0,0694	$1681.4^{1)}$	53.4 ¹⁾





2900 PSI: 81.0 % 4650 PSI : 80.8 %

MAX RATINGS - M5B* SERIES

012 & 018



023 - 028 - 036

045







- These are running condition limits ; for starting performances see page 6.

- Intermittent conditions : do not exceed 6 seconds per minute of rotation.

- Typical curves, at 115 SUS / 113° F.

- For higher specifications or for operating speed under 100 RPM, please consult our technical department.

ORDERING CODE - M5B - M5BS SERIES



Direction of rotation (view on shaft end)

N = bi-directional



PERMISSIBLE AXIAL AND RADIAL LOADS





Parker Hannifin Denison Vane Pump Division Vierzon - France

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M10 Σ M18 x 1,5 3/8" - 16 UNC M5B 88,4 m 0 SAE 9/16" - 18 M18 x 1,5 M10 Σ e **M5BS** 8,68 3/8" - 16 UNC 0 2 Drain code Port code ØΑ ØΒ ØE ØG ØΓ Ω C [T_ Η \mathbf{k} ſ

ORDERING CODE - M5BF SERIES



◆ L10=2000 -×- - ∟10=5000

1200

Parker Hannifin Denison Vane Pump Division Vierzon - France

200

400

600

Axial load Fa [lbs]

800

1000

0 0



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Port code ØA 2

Drain code

ØB